

On Global Convergence of Fractional Fliess Operators with Applications to Bilinear Systems

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Abstract—A common representation for the input-output map of a nonlinear control system is the Chen-Fliess functional series or Fliess operator. The objective of this paper is to further develop a generalization of this class of operators, so called *fractional Fliess operators*. These are functional series whose iterated integrals are defined in terms of fractional integrals and where the series coefficients can have a fractional Gevrey growth rate. Here the existing convergence analysis is expanded to handle fractional integrated integrals for a class of L_1 inputs. The results are applied to represent the input-output map of a fractional bilinear state space system.

Keywords—Fractional systems, Chen-Fliess series, bilinear systems

I. INTRODUCTION

A common representation for the input-output map of a nonlinear control system is the Chen-Fliess functional series or Fliess operator [2], [8]. It can be viewed as a noncommutative generalization of a Taylor series, and its algebraic nature is especially well suited for describing system interconnections [4], [6] and solving system inversion problems [5] in a nonlinear setting. The objective of this paper is to further develop a generalization of this class of operators, so called *fractional Fliess operators*. These are functional series whose iterated integrals are defined in terms of fractional integrals and where the series coefficients can have a fractional Gevrey growth rate. The idea was first proposed by the authors in [18] and applied mainly in the context of fractional linear systems. A sufficient condition for a kind of global convergence was given for the special case where only the coefficients have this fractional nature. Here the convergence analysis is expanded to handle fractional integrated integrals of L_1 inputs dominated by any monomial t^ϵ , where $\epsilon > 0$. The results are applied to represent the input-output map of a fractional bilinear state space system. There are in fact two approaches possible, one that is compatible with the Riemann-Liouville fractional derivative and the other with the Caputo fractional derivative. Both approaches are pursued in parallel. In the process, a fractional notion of a causal Volterra series is also identified.

The presentation is organized as follows. In the next section, some fundamentals from fractional calculus are briefly summarized. In Section III, the notion of a fractional Fliess operator is described and the new convergence analysis is presented. The concept is then applied in Section IV to fractional bilinear systems.

II. PRELIMINARIES: FRACTIONAL CALCULUS

Fractional calculus and fractional system theory are well developed areas with a variety of applications. The main definitions and results concerning fractional calculus presented here are largely based on [1], [10], [14], [15], [17]. Assume $\alpha, \beta \in \mathbb{R}$, and f is a real-valued function defined on $[0, T]$. Under suitable restrictions on f , which will be assumed throughout, the following fractional extensions of integration and differentiation are well defined [1].

Definition 2.1: The Riemann-Liouville fractional integral for any $\alpha > 0$ and $t \in [0, T]$ is defined by

$$I^\alpha f(t) = \frac{1}{\Gamma(\alpha)} \int_0^t f(\tau)(t-\tau)^{\alpha-1} d\tau,$$

where Γ is the gamma function. In addition, $I^0 f(t) := f(t)$.

Definition 2.2: The Riemann-Liouville fractional derivative for any $n-1 < \alpha \leq n$ with $n \in \mathbb{N}$ and $t \in [0, T]$ is defined by

$$D^\alpha f(t) = \frac{d^n}{dt^n} I^{n-\alpha} f(t).$$

Definition 2.3: The Caputo fractional derivative for any $n-1 < \alpha \leq n$ with $n \in \mathbb{N}$, $t \in [0, T]$, and n times differentiable function f is defined by

$${}^C D^\alpha f(t) = I^{n-\alpha} \left(\frac{d^n f}{dt^n} \right) (t).$$

Lemma 2.1: The Riemann-Liouville and Caputo fractional derivatives are related by

$${}^C D^\alpha f(t) = D^\alpha (f(t) - f(0)).$$

Lemma 2.2: The following relations hold when $0 < \alpha$ and f, g are real-valued measurable functions on $[0, T]$:

- 1) $f(t) = I^{1-\alpha} f(0) \frac{t^{\alpha-1}}{\Gamma(\alpha)} + I^\alpha D^\alpha f(t)$, $\alpha \leq 1$
- 2) $D^\alpha (f \circ g)(t) = \sum_{k=0}^{\infty} \frac{1}{k!} \left(\sum_{r=0}^k \binom{k}{r} (-g(t))^r D^\alpha g^{k-r}(t) \right) \frac{d^k}{dg^k} f(g(t))$.

This last relation above is the chain rule for fractional calculus introduced by Osler [14, equations (3.4)-(3.5) with $z = t$, $g(t) = t$ and $F(t, w) = 1$].

Example 2.1: In the case where $\alpha = 1$ in Lemma 2.2, part 2, it follows that

$$\frac{d}{dt} (f \circ g)(t)$$

$$\begin{aligned}
&= \sum_{k=0}^{\infty} \frac{1}{k!} \left(\sum_{r=0}^k \binom{k}{r} (-g(t))^r \frac{d}{dt} g^{k-r}(t) \right) \frac{d^k}{dg^k} f(g(t)) \\
&= \left(\frac{d}{dt} \mathbb{1}(t) \right) f(g(t)) + \left(\frac{d}{dt} g(t) - g(t) \frac{d}{dt} \mathbb{1}(t) \right) \frac{d}{dg} f(g(t)) \\
&+ \frac{1}{2} \left(\frac{d}{dt} g^2(t) - 2g(t) \frac{d}{dt} g(t) + g^2(t) \frac{d}{dt} \mathbb{1}(t) \right) \frac{d^2}{dg^2} f(g(t)) \\
&+ \frac{1}{2} \left(\frac{d}{dt} g^3(t) - 3g(t) \frac{d}{dt} g^2(t) + 3g^2(t) \frac{d}{dt} g(t) \right. \\
&\left. - g^3(t) \frac{d}{dt} \mathbb{1}(t) \right) \frac{d^3}{dg^3} f(g(t)) + \dots,
\end{aligned}$$

where $\mathbb{1}$ is the unit step function. Since $\frac{d}{dt} g^k(t) = \sum_{r=1}^{k-1} \binom{k}{r} (-g(t))^r \frac{d}{dt} g^{k-r}(t)$, $k \in \mathbb{N}$ and $k > 1$ [3], and $\frac{d}{dt} \mathbb{1}(t) = 0$ for $t > 0$, all the terms are zero except the one corresponding to $k = 1$. This term gives the usual chain rule. \square

Corollary 2.1: [3] If $\alpha = N \in \mathbb{N}$ then Lemma 2.2, part 2 reduces to

$$\begin{aligned}
&\frac{d^N}{dt^N} (f \circ g)(t) = \\
&\sum_{k=0}^N \frac{1}{k!} \left(\sum_{r=0}^k \binom{k}{r} (-g(t))^r \frac{d^N}{dt^N} g^{k-r}(t) \right) \frac{d^k}{dg^k} f(g(t)).
\end{aligned}$$

Let P_q denote the class of polynomials with real coefficients and having degree q .

Corollary 2.2: Suppose $f \in P_q$ then Lemma 2.2, part 2 becomes

$$\begin{aligned}
&D^\alpha (f \circ g)(t) = \\
&\sum_{k=0}^q \frac{1}{k!} \left(\sum_{r=0}^k \binom{k}{r} (-g(t))^r D^\alpha g^{k-r}(t) \right) \frac{d^k}{dg^k} f(g(t)).
\end{aligned}$$

Example 2.2: In the case where $f \in P_1$, observe

$$\begin{aligned}
&D^\alpha (f \circ g)(t) = (D^\alpha \mathbb{1}(t)) f(g(t)) \\
&+ (D^\alpha g(t) - g(t) D^\alpha \mathbb{1}(t)) \frac{d}{dg} f(g(t)).
\end{aligned}$$

\square

The next definition and lemma are used throughout the paper.

Definition 2.4: [11] The *matrix Mittag-Leffler function* is

$$\mathcal{E}_{\alpha, \beta}(At) = \sum_{k=0}^{\infty} \frac{(At)^k}{\Gamma(\alpha k + \beta)},$$

where t is real-valued, $A \in \mathbb{R}^{n \times n}$, and α, β are positive real numbers. In particular, $\mathcal{E}_{1,1}(At) = e^{At}$ is the usual matrix exponential.

Lemma 2.3: The following identities are easily verified for real numbers $\alpha, \beta > 0$ and real-valued function f :

$$\begin{aligned}
1) \quad &I^{\alpha} t^{\beta} = t^{\alpha+\beta} \frac{\Gamma(\beta+1)}{\Gamma(\alpha+\beta+1)} \\
2) \quad &\sum_{k=0}^{\infty} A^k I^{\alpha k} \mathbb{1}(t) = \mathcal{E}_{\alpha,1}(At^\alpha)
\end{aligned}$$

$$3) \quad \sum_{k=1}^{\infty} A^{k-1} I^{\alpha k} f(t) = (t^{\alpha-1} \mathcal{E}_{\alpha,\alpha}(At^\alpha)) * f(t).$$

Here $*$ refers to the usual convolution product.

III. GLOBAL CONVERGENCE OF FRACTIONAL FLIESS OPERATORS

Let $X = \{x_0, x_1, \dots, x_m\}$ be an alphabet and X^* the free monoid comprised of all words over X (including the empty word \emptyset) under the catenation product. A formal power series in X is any mapping of the form $X^* \rightarrow \mathbb{R}^\ell$, and the set of all such mappings will be denoted by $\mathbb{R}^\ell \langle\langle X \rangle\rangle$. The image of η under c is written as (c, η) . For each $c \in \mathbb{R}^\ell \langle\langle X \rangle\rangle$, one can formally associate an m input, ℓ output operator, F_c , as described next. Let $p \geq 1$ and $T > 0$ be given. For a Lebesgue measurable function $u : [0, T] \rightarrow \mathbb{R}^m$, define $\|u\|_p = \max\{\|u_i\|_p : 1 \leq i \leq m\}$, where $\|u_i\|_p$ is the usual L_p -norm for a measurable real-valued function, u_i , defined on $[0, T]$. Let $L_p^m[0, T]$ denote the set of all measurable functions defined on $[0, T]$ having a finite $\|\cdot\|_p$ norm and $B_p^m(R)[0, T] := \{u \in L_p^m[0, T] : \|u\|_p \leq R\}$. The next two definitions are fundamental.

Definition 3.1: [18] Let $0 < \alpha \leq 1$ and $T \in \mathbb{R}$ be fixed. The *fractional iterated integral* for any $\eta = x_i \eta' \in X^*$ is the mapping $E_\eta^\alpha : L_1^m[0, T] \rightarrow \mathbb{R}[0, T]$ defined by the recursion

$$E_{x_i \eta'}^\alpha[u](t) = I^\alpha [u_i(\tau) E_{\eta'}^\alpha[u](\tau)](t),$$

where $E_\emptyset^\alpha := 1$ and

$$u_0(t) := \begin{cases} \frac{t^{\alpha-1}}{\Gamma(\alpha)} : \text{Riemann-Liouville derivative approach} \\ \mathbb{1}(t) : \text{Caputo derivative approach.} \end{cases}$$

Note that when $\alpha = 1$, the resulting iterated integrals are continuous. But when $0 < \alpha < 1$ this is so if, for example, the functions u_i , $i = 1, 2, \dots, m$ are all continuous. Weaker sufficient conditions also exist, see [1, Definition 2.1.1].

Definition 3.2: [18] For any $c \in \mathbb{R}^\ell \langle\langle X \rangle\rangle$ and $0 < \alpha \leq 1$ the *fractional Fliess operator* is defined formally by

$$F_c^\alpha[u](t) = \sum_{\eta \in X^*} (c, \eta) E_\eta^\alpha[u](t).$$

The operator has *Gevrey order* $s \in \mathbb{R}$ if there exists real constants $K, M > 0$ such that

$$|(c, \eta)| \leq KM^{|\eta|} (|\eta|!)^s, \quad \forall \eta \in X^*,$$

and s is the smallest number having this property.

The next two technical lemmas will be useful.

Lemma 3.1: [18] For any integer $n \geq 0$ and $0 < r \leq 1$ such that $nr \gg 1$ it follows that

$$\Gamma(rn+1) \approx \frac{1}{n^{(1-r)/2}} K_r M_r^n (n!)^r,$$

where $K_r := ((2\pi)^{1-r} r)^{1/2}$ and $M_r := r^r$.

Lemma 3.2: For any integer $n, k \geq 0$ and $0 < r \leq 1$ such that $rn, rk \gg 1$ it follows that

$$\begin{aligned}
&\Gamma(r(nk+n+k)+1) \Gamma(r(n+1)+1) \Gamma(r(k+1)+1) \\
&\leq \Gamma(r(n+1)(k+1)+1) \Gamma(rn+1) \Gamma(rk+1).
\end{aligned}$$

Proof: Applying the approximation in Lemma 3.1 for each gamma function on the left-hand side of the proposed inequality gives

$$\Gamma(r(nk+n+k)+1) \Gamma(r(n+1)+1) \Gamma(r(k+1)+1)$$

$$\approx \frac{K_r^3 M_r^{nk+2n+2k+2} ((nk+n+k)!(n+1)!(k+1)!)^r}{((nk+n+k)(n+1)(k+1))^{(1-r)/2}},$$

where $K_r := ((2\pi)^{1-r} r)^{1/2}$ and $M_r := r^r$. It is clear that $(nk+n+k)!(n+1)!(k+1)! = \frac{nk(nk+n+k+1)!n!k!}{nk+n+k+1} \leq (nk+n+k+1)!n!k!$

and

$$(nk+n+k)(n+1)(k+1) \geq nk(n+1)(k+1).$$

It then follows that

$$\begin{aligned} & \Gamma(r(nk+n+k)+1)\Gamma(r(n+1)+1)\Gamma(r(k+1)+1) \\ & \leq \frac{K_r^3 M_r^{nk+2n+2k+1} ((nk+n+k+1)!n!k!)^r}{((n+1)(k+1)nk)^{(1-r)/2}} \\ & \approx \Gamma(r(n+1)(k+1)+1)\Gamma(rn+1)\Gamma(rk+1), \end{aligned}$$

again using Lemma 3.1 in the final step. \blacksquare

The next lemma provides upper bounds for certain fractional iterated integrals. Henceforth, the focus is on the single-input, single-output (SISO) case ($m = \ell = 1$).

Lemma 3.3: Let $X = \{x_0, x_1\}$. For any $x_i \in X$, integers $k, \gamma \geq 0$ and $0 < \alpha \leq 1$

$$E_{x_i}^\alpha [u](t) \leq \frac{(I^\alpha u_i(t))^k}{\Gamma(\alpha k + 1)},$$

where $u(t) = t^{\alpha\gamma}$, t is real valued, and the Caputo derivative approach is used.

Proof: The fractional iterated integral when $i = 0$ is

$$\begin{aligned} E_{x_0}^\alpha [t^{\alpha\gamma}](t) &= I^{\alpha k} \mathbb{1}(t) = \frac{t^{\alpha k}}{\Gamma(\alpha k + 1)} \\ &\leq \left(\frac{t^\alpha}{\Gamma(\alpha + 1)} \right)^k \frac{1}{\Gamma(\alpha k + 1)}, \end{aligned}$$

since $\Gamma(\alpha + 1) \leq 1$ when $1 < \alpha + 1 \leq 2$. Applying Lemma 2.3, part 1 gives

$$E_{x_0}^\alpha [t^{\alpha\gamma}](t) \leq \frac{(I^\alpha \mathbb{1}(t))^k}{\Gamma(\alpha k + 1)}.$$

On the other hand, when $i = 1$ an inductive proof on k can be used. The claim is clearly true when $k = 0$. When $k = 1$ observe that

$$E_{x_1}^\alpha [t^{\alpha\gamma}](t) = I^{\alpha} t^{\alpha\gamma} \leq \frac{I^\alpha t^{\alpha\gamma}}{\Gamma(\alpha + 1)},$$

since $\Gamma(\alpha + 1) \leq 1$. Now suppose the identity in question holds up to some fixed $k \geq 0$. Then

$$E_{x_1}^\alpha [t^{\alpha\gamma}](t) = I^\alpha [t^{\alpha\gamma} E_{x_1}^\alpha [t^{\alpha\gamma}]].$$

From the induction hypothesis, it follows that

$$\begin{aligned} E_{x_1}^\alpha [t^{\alpha\gamma}](t) &\leq I^\alpha \left(t^{\alpha\gamma} \frac{(I^\alpha t^{\alpha\gamma})^k}{\Gamma(\alpha k + 1)} \right) \\ &= \frac{\Gamma(\alpha\gamma + 1)^k}{\Gamma(\alpha k + 1)\Gamma(\alpha(\gamma + 1) + 1)^k} I^{\alpha} t^{\alpha(\gamma k + \gamma + k)}. \end{aligned}$$

Applying Lemma 2.3, part 1 gives

$$\begin{aligned} & E_{x_1}^\alpha [t^{\alpha\gamma}](t) \\ & \leq \frac{\Gamma(\alpha\gamma + 1)^k \Gamma(\alpha(\gamma k + \gamma + k) + 1) t^{\alpha(\gamma + 1)(k + 1)}}{\Gamma(\alpha k + 1)\Gamma(\alpha(\gamma + 1) + 1)^k \Gamma(\alpha(\gamma + 1)(k + 1) + 1)}. \end{aligned}$$

Finally, employing Lemma 3.2 yields

$$\begin{aligned} E_{x_1}^\alpha [t^{\alpha\gamma}](t) &\leq \frac{\Gamma(\alpha\gamma + 1)^{k+1} t^{\alpha(\gamma + 1)(k + 1)}}{\Gamma(\alpha(k + 1) + 1)\Gamma(\alpha(\gamma + 1) + 1)^{k+1}} \\ &= \frac{(I^\alpha t^{\alpha\gamma})^{k+1}}{\Gamma(\alpha(k + 1) + 1)}. \end{aligned}$$

Therefore, the inequality holds for all $k \geq 0$. \blacksquare

The main result of this section is the following theorem.

Theorem 3.1: Let $X = \{x_0, x_1\}$. Suppose $c \in \mathbb{R}\langle\langle X \rangle\rangle$ is a Gevrey series of order $0 \leq s < 1$. If $0 < s < \alpha \leq 1$ then for any $u \in L_{1/\alpha}^1[0, T]$ where $|u(t)| \leq t^{\alpha\gamma}$ for all $t \in [0, T]$ with $\gamma \in \mathbb{N}$, the series

$$y(t) = F_c^\alpha [u](t) = \sum_{\eta \in X^*} (c, \eta) E_\eta^\alpha [u](t),$$

converges absolutely and uniformly on $[0, T]$ for any $T > 0$ assuming the Caputo derivative approach is used.

Proof: Fix some $T > 0$. Pick any $u \in L_{1/\alpha}^1[0, T]$ where $|u(t)| \leq t^{\alpha\gamma}$, $\forall t \in [0, T]$ with $\gamma \in \mathbb{N}$. Let $R = \max\{C_{\alpha, \gamma} \|t^{\alpha\gamma}\|_1, T^\alpha / \Gamma(\alpha + 1)\}$ on $[0, T]$ with $C_{\alpha, \gamma} := (\gamma + 1)^\alpha \Gamma(\alpha\gamma + 1) / \Gamma(\alpha(\gamma + 1) + 1)$. Observe from Lemma 3.3 it follows that

$$\begin{aligned} F_c^\alpha [u](t) &\leq \sum_{\eta \in X^*} |(c, \eta)| |E_\eta^\alpha [u](t)| \\ &\leq \sum_{k=0}^{\infty} KM^k (k!)^s \sum_{\eta \in X^k} E_\eta^\alpha [|u|](t) \\ &\leq \sum_{k=0}^{\infty} KM^k (k!)^s \sum_{\eta \in X^k} E_\eta^\alpha [t^{\alpha\gamma}] \\ &\leq \sum_{k=0}^{\infty} KM^k (k!)^s \frac{R^k}{\Gamma(\alpha k + 1)}, \end{aligned}$$

since R can be rewritten as $R = \max\{I^\alpha u_0(t), I^\alpha u_1(t)\}$ on $[0, T]$ using the identities $I^\alpha \mathbb{1}(t) = t^\alpha / \Gamma(\alpha + 1)$ and $I^\alpha t^{\alpha\gamma} = C_{\alpha, \gamma} \|t^{\alpha\gamma}\|_1$. In which case,

$$F_c^\alpha [u](t) \leq K \sum_{k=0}^{\infty} (MR)^k \frac{(k!)^s}{\Gamma(\alpha k + 1)}.$$

Applying the ratio test to the sequence $a_k := (k!)^s / \Gamma(\alpha k + 1)$, $k \geq 0$:

$$\begin{aligned} \lim_{k \rightarrow \infty} \left| \frac{a_{k+1}}{a_k} \right| &= \lim_{k \rightarrow \infty} \frac{((k+1)!)^s \Gamma(\alpha k + 1)}{\Gamma(\alpha(k+1) + 1) (k!)^s} \\ &= \lim_{k \rightarrow \infty} \frac{(k+1)^s \Gamma(\alpha(k+1) + 1)}{\Gamma(\alpha k + 1)}. \end{aligned}$$

Using Lemma 3.1 for each gamma function and the fact that $0 < \alpha - s \leq 1$, it follows that

$$\begin{aligned} \lim_{k \rightarrow \infty} \left| \frac{a_{k+1}}{a_k} \right| &= \frac{1}{M_\alpha} \lim_{k \rightarrow \infty} \left(1 + \frac{1}{k} \right)^{(1-\alpha)/2} \frac{1}{(k+1)^{\alpha-s}} \\ &= \frac{1}{M_\alpha} \lim_{k \rightarrow \infty} \frac{1}{(k+1)^{\alpha-s}} = 0, \end{aligned}$$

where $M_\alpha := \alpha^\alpha$. Thus, the series $F_c^\alpha [u](t)$ converges absolutely and uniformly on $[0, T]$. \blacksquare

The notion of convergence described above is referred to as *global* since there is no a priori upper bound on either γ

or T . As expected, Theorem 3.1 is consistent with the fact that Fliess operators are known to be globally convergent when $\alpha = 1$ and $0 \leq s < 1$ [18]. An analogous theorem holds when the Riemann-Liouville approach is taken in light of Lemma 2.1.

IV. FRACTIONAL BILINEAR SYSTEMS

In this section the Fliess operator representation of the input-output map of a SISO fractional bilinear system is given for the Riemann-Liouville derivative approach and the Caputo derivative approach. The development also suggests the notion of a fractional Volterra series, so the idea is presented in the final subsection.

A. Riemann-Liouville fractional derivative approach

Consider a SISO bilinear system

$$D^\alpha z = N_0 z + N_1 z u, \quad z(0) = z_0 \quad (1a)$$

$$y = \lambda z, \quad (1b)$$

where $N_0, N_1 \in \mathbb{R}^{n \times n}$, $\lambda \in \mathbb{R}^{1 \times n}$, and $0 < \alpha \leq 1$. The state equation can be written in integral form using Lemma 2.2, part 1 as

$$z(t) = I^{1-\alpha} z(0) \left[\frac{t^{\alpha-1}}{\Gamma(\alpha)} \right] + N_0 I^\alpha z(t) + N_1 I^\alpha z(t) u(t). \quad (2)$$

Since integration and differentiation are defined component-wise, there is no loss of generality in the following analysis by assuming $n = 1$. For any $F \in P_1$, the differential chain rule in integral form given in Example 2.2 becomes

$$D^\alpha F(z(t)) = (D^\alpha \mathbf{1}(t)) F(z(t)) + (D^\alpha z(t) - z(t) D^\alpha \mathbf{1}(t)) \frac{d}{dz} F(z(t)).$$

Using this result and Lemma 2.2, part 1 gives

$$\begin{aligned} F(z(t)) &= I^{1-\alpha} F(z(0)) \left[\frac{t^{\alpha-1}}{\Gamma(\alpha)} \right] + I^\alpha ((D^\alpha \mathbf{1}(t)) F(z(t))) \\ &\quad + N_0 I^\alpha \left(z(t) \frac{d}{dz} F(z(t)) \right) + N_1 I^\alpha \left(z(t) u(t) \frac{d}{dz} F(z(t)) \right) \\ &\quad - I^\alpha \left((D^\alpha \mathbf{1}(t)) z(t) \frac{d}{dz} F(z(t)) \right). \end{aligned}$$

Now let $F(z(t))$ be replaced by $N_i z(t)$, $i = 0, 1$ and substitute back into (2). This yields

$$\begin{aligned} z(t) &= I^{1-\alpha} z(0) \left[\frac{t^{\alpha-1}}{\Gamma(\alpha)} \right] + N_0 I^{1-\alpha} z(0) I^\alpha \left[\frac{t^{\alpha-1}}{\Gamma(\alpha)} \right] \\ &\quad + N_1 I^{1-\alpha} z(0) I^\alpha \left[u(t) \frac{t^{\alpha-1}}{\Gamma(\alpha)} \right] + N_0^2 I^{2\alpha} z(t) \\ &\quad + N_0 N_1 I^{2\alpha} (z(t) u(t)) + N_1 N_0 I^\alpha (I^\alpha z(t) u(t)) \\ &\quad + N_1^2 I^\alpha (I^\alpha (z(t) u(t)) u(t)). \end{aligned}$$

Repeating this procedure, let $F(z(t))$ be replaced by $N_i N_j z(t)$, $i, j = 0, 1$ and substitute back into the equation above. This gives

$$\begin{aligned} z(t) &= I^{1-\alpha} z(0) \left[\frac{t^{\alpha-1}}{\Gamma(\alpha)} \right] + N_0 I^{1-\alpha} z(0) I^\alpha \left[\frac{t^{\alpha-1}}{\Gamma(\alpha)} \right] \\ &\quad + N_1 I^{1-\alpha} z(0) I^\alpha \left[u(t) \frac{t^{\alpha-1}}{\Gamma(\alpha)} \right] + N_0^2 I^{1-\alpha} z(0) I^{2\alpha} \left[\frac{t^{\alpha-1}}{\Gamma(\alpha)} \right] \\ &\quad + N_0 N_1 I^{1-\alpha} z(0) I^{2\alpha} \left[u(t) \frac{t^{\alpha-1}}{\Gamma(\alpha)} \right] + N_1^2 I^{1-\alpha} z(0) I^\alpha (u(t) I^\alpha u(t)) \end{aligned}$$

$$+ N_1 N_0 I^{1-\alpha} z(0) I^\alpha \left[u(t) I^\alpha \left[\frac{t^{\alpha-1}}{\Gamma(\alpha)} \right] \right] + R_2(z(t), u(t)),$$

where $R_2(z(t), u(t))$ contains all the integrals depending explicitly on $z(t)$ and $u(t)$. Continuing in this manner produces in the limit a fractional form of the usual Peano-Baker formula [16]. So the series solution of (1a) is

$$z(t) = \sum_{\eta \in X^*} (c_\eta, \eta) E_\eta^\alpha [u](t), \quad (3)$$

where $u_0(t) := t^{\alpha-1}/\Gamma(\alpha)$ as indicated in Definition 3.1, and the coefficients of the generating series for $y(t) = \lambda z(t) = F_c^\alpha [u](t)$ are

$$(c, \eta) = \lambda N_{i_k} \cdots N_{i_1} I^{1-\alpha} z(0) \quad (4)$$

for $\eta = x_{i_k} \cdots x_{i_1}$. As a check, write (3) in the form

$$\begin{aligned} z(t) &= I^{1-\alpha} z(0) \left[\frac{t^{\alpha-1}}{\Gamma(\alpha)} \right] \\ &\quad + \sum_{i=0}^1 \sum_{k=0}^{\infty} \sum_{i_0, \dots, i_k=0}^1 N_{i_k} N_{i_{k-1}} \cdots N_{i_1} I^{1-\alpha} z(0) \\ &\quad I^\alpha [u_i(\tau) E_{x_{i_k} \cdots x_{i_1}}^\alpha (u(\tau))](t), \end{aligned}$$

and take the Riemann-Liouville derivative of order α so that

$$\begin{aligned} D^\alpha z(t) &= \sum_{k=0}^{\infty} \sum_{i_0, \dots, i_k=0}^1 N_0 N_{i_k} \cdots N_{i_1} I^{1-\alpha} z(0) u_0(t) E_{x_{i_k} \cdots x_{i_1}}^\alpha [u](t) \\ &\quad + \sum_{k=0}^{\infty} \sum_{i_0, \dots, i_k=0}^1 N_1 N_{i_k} \cdots N_{i_1} I^{1-\alpha} z(0) u_1(t) E_{x_{i_k} \cdots x_{i_1}}^\alpha [u](t) \\ &= N_0 z(t) + N_1 z(t) u(t), \end{aligned}$$

which is consistent with (1a). Also note that in this Riemann-Liouville approach, the coefficients are not explicit functions of $z(0)$, but rather in terms of $I^{1-\alpha} z(0)$. This fractional initial condition can be written as

$$I^{1-\alpha} z(t) \Big|_{t=0} = \frac{z(t) \Gamma(\alpha)}{t^{\alpha-1}} \Big|_{t=0}$$

[12], [17].

B. Caputo fractional derivative approach

Consider now a SISO bilinear system

$${}^C D^\alpha z = N_0 z + N_1 z u, \quad z(0) = z_0 \quad (5a)$$

$$y = \lambda z, \quad (5b)$$

where $N_0, N_1 \in \mathbb{R}^{n \times n}$, $\lambda \in \mathbb{R}^{1 \times n}$, and $0 < \alpha \leq 1$. The state equation can be written in integral form using Lemma 2.1 and Lemma 2.2, part 1 as

$$z(t) = z(0) + N_0 I^\alpha z(t) + N_1 I^\alpha (z(t) u(t)). \quad (6)$$

Following the same procedure as in the previous subsection and assuming $n = 1$ yields

$$\begin{aligned} F(z(t)) &= F(z(0)) + I^\alpha ((D^\alpha \mathbf{1}(t)) (F(z(t)) - F(z(0)))) \\ &\quad + N_0 I^\alpha \left(z(t) \frac{d}{dz} F(z(t)) \right) + N_1 I^\alpha \left(z(t) u(t) \frac{d}{dz} F(z(t)) \right) \\ &\quad - I^\alpha \left((D^\alpha \mathbf{1}(t)) (z(t) - z(0)) \frac{d}{dz} F(z(t)) \right). \end{aligned}$$

Now let $F(z(t))$ be replaced by $N_i z(t)$, $i = 0, 1$ and substitute back into (6). This yields

$$z(t) = z_0 + N_0 z_0 I^\alpha \mathbf{1}(t) + N_1 z_0 I^\alpha u(t) + R_1(z(t), u(t)),$$

where $R_1(z(t), u(t))$ contains all the integrals depending explicitly on $z(t)$ and $u(t)$. Continuing in this way produces the Caputo analogue of (3)-(4), namely, the series solution of (5a) is

$$z(t) = \sum_{\eta \in X^*} (c_z, \eta) E_\eta^\alpha [u](t), \quad (7)$$

where now $u_0(t) := \mathbb{1}(t)$ as indicated in Definition 3.1. The coefficients of the generating series for $y(t) = \lambda z(t) = F_c^\alpha [u](t)$ are

$$(c, \eta) = \lambda N_{i_k} \cdots N_{i_1} z_0 \quad (8)$$

for $\eta = x_{i_k} \cdots x_{i_1}$. Again as a check, a straightforward calculation shows that the Caputo derivative of (7) gives (5a) as expected. The main differences between the Caputo and Riemann-Liouville cases are the presence of $z(0)$ instead of $I^{1-\alpha} z(0)$ in the series coefficients and the factor of $\mathbb{1}(t)$ instead of $t^{\alpha-1}/\Gamma(\alpha)$ in the iterated integrals. Henceforth, the focus is mainly on the Caputo approach since the coefficients and the iterated integrals are easier to compute.

C. Fractional Volterra series

A generalization of a Volterra series for a fractional bilinear system is given in the next theorem.

Theorem 4.1: The solution $y(t) = \lambda z(t) = F_c^\alpha [u](t)$ of a bilinear system in the Caputo sense (5) can be written in terms of the matrix Mittag-Leffler function as

$$y(t) = w_0(t) + \sum_{k=1}^{\infty} \int_0^t \int_0^{\tau_k} \cdots \int_0^{\tau_2} w_k(t, \tau_k, \dots, \tau_1) u(\tau_k) \cdots u(\tau_1) d\tau_1 \cdots d\tau_k,$$

where

$$\begin{aligned} w_0(t) &= \lambda \mathcal{E}_{\alpha,1}(N_0 t^\alpha) z_0 \\ w_k(t, \tau_k, \dots, \tau_1) &= \lambda (t - \tau_k)^{\alpha-1} \mathcal{E}_{\alpha,\alpha}(N_0(t - \tau_k)^\alpha) \\ &\quad N_1(\tau_k - \tau_{k-1})^{\alpha-1} \mathcal{E}_{\alpha,\alpha}(N_0(\tau_k - \tau_{k-1})^\alpha) \\ &\quad \cdots N_1(\tau_2 - \tau_1)^{\alpha-1} \mathcal{E}_{\alpha,\alpha}(N_0(\tau_2 - \tau_1)^\alpha) \\ &\quad N_1 \mathcal{E}_{\alpha,1}(N_0 \tau_1^\alpha) z_0, \quad k \geq 1. \end{aligned}$$

Proof: Since each word $\eta = x_{i_k} \cdots x_{i_1} \in X^*$ can be rewritten uniquely in the form $x_0^{n_k} x_1 x_0^{n_{k-1}} x_1 \cdots x_0^{n_1} x_1 x_0^{n_0}$, it follows from (7)-(8) that

$$y(t) = \sum_{k=0}^{\infty} \sum_{n_0, \dots, n_k=0}^{\infty} \lambda N_0^{n_k} N_1 N_0^{n_{k-1}} \cdots N_1 N_0^{n_0} z_0 E_{x_0^{n_k} x_1 x_0^{n_{k-1}} \cdots x_1 x_0^{n_0}}^\alpha [u](t).$$

The claim is that $y = \sum_{k \geq 0} y_k$, where

$$\begin{aligned} y_k(t) &:= \sum_{n_0, \dots, n_k=0}^{\infty} \lambda N_0^{n_k} N_1 N_0^{n_{k-1}} \cdots N_1 N_0^{n_0} z_0 \\ &\quad E_{x_0^{n_k} x_1 x_0^{n_{k-1}} \cdots x_1 x_0^{n_0}}^\alpha [u](t) \\ &= \sum_{n_0, \dots, n_k=0}^{\infty} \int_0^t \int_0^{\tau_k} \cdots \int_0^{\tau_2} w_k(t, \tau_k, \dots, \tau_1) \\ &\quad u(\tau_k) \cdots u(\tau_1) d\tau_1 \cdots d\tau_k \end{aligned}$$

for $k \geq 1$ and $y_0 := \sum_{n_0 \geq 0} \lambda N_0^{n_0} z_0 E_{x_0^{n_0}}^\alpha [u] = w_0$. The expressions for y_k are proved by induction on k . Observe

that when $k = 0$

$$y_0(t) = \sum_{n_0=0}^{\infty} \lambda N_0^{n_0} z_0 I^{\alpha n_0} \mathbb{1}(t),$$

and using Lemma 2.3, part 2 yields $y_0(t) = \lambda \mathcal{E}_{\alpha,1}(N_0 t^\alpha) z_0 = w_0(t)$. When $k = 1$, it follows via Lemma 2.3, part 3 that

$$\begin{aligned} y_1(t) &= \sum_{n_0, n_1=0}^{\infty} \lambda N_0^{n_1} N_1 N_0^{n_0} z_0 I^{\alpha(n_1+1)}(u(t) I^{\alpha n_0} \mathbb{1}(t)) \\ &= \sum_{n_0=0}^{\infty} (\lambda t^{\alpha-1} \mathcal{E}_{\alpha,\alpha}(N_0 t^\alpha) N_1 N_0^{n_0} z_0) * (u(t) I^{\alpha n_0} \mathbb{1}(t)). \end{aligned}$$

Applying next Lemma 2.3, part 2 yields

$$\begin{aligned} y_1(t) &= \int_0^t \lambda (t - \tau)^{\alpha-1} \mathcal{E}_{\alpha,\alpha}(N_0(t - \tau)^\alpha) N_1 \mathcal{E}_{\alpha,1}(N_0 \tau_1^\alpha) \\ &\quad z_0 u(\tau) d\tau \\ &= \int_0^t w_1(t, \tau_1) u(\tau_1) d\tau_1. \end{aligned}$$

Now suppose the identity in question holds for all terms up to some fixed $k \geq 0$. Then

$$\begin{aligned} y_{k+1}(t) &= \sum_{n_0, \dots, n_{k+1}=0}^{\infty} \lambda N_0^{n_{k+1}} N_1 N_0^{n_k} \cdots N_1 N_0^{n_0} z_0 \\ &\quad I^{\alpha(n_{k+1}+1)}(u(t) E_{x_0^{n_k} x_1 x_0^{n_{k-1}} \cdots x_1 x_0^{n_0}}^\alpha [u](t)), \end{aligned}$$

and Lemma 2.3, part 3 gives

$$\begin{aligned} y_{k+1}(t) &= \sum_{n_0, \dots, n_k=0}^{\infty} \lambda t^{\alpha-1} \mathcal{E}_{\alpha,\alpha}(N_0 t^\alpha) N_1 N_0^{n_k} \cdots N_1 N_0^{n_0} z_0 \\ &\quad * (u(t) E_{x_0^{n_k} x_1 x_0^{n_{k-1}} \cdots x_1 x_0^{n_0}}^\alpha [u](t)) \\ &= \sum_{n_0, \dots, n_k=0}^{\infty} \int_0^t \lambda (t - \tau_{k+1})^{\alpha-1} \mathcal{E}_{\alpha,\alpha}(N_0(t - \tau_{k+1})^\alpha) \\ &\quad N_1 N_0^{n_k} \cdots N_1 N_0^{n_0} z_0 \\ &\quad u(\tau_{k+1}) E_{x_0^{n_k} x_1 x_0^{n_{k-1}} \cdots x_1 x_0^{n_0}}^\alpha [u](t) d\tau_{k+1}. \end{aligned}$$

Finally, from the induction hypothesis, it follows that

$$\begin{aligned} y_{k+1}(t) &= \int_0^t \int_0^{\tau_{k+1}} \cdots \int_0^{\tau_2} \lambda (t - \tau_{k+1})^{\alpha-1} \\ &\quad \mathcal{E}_{\alpha,\alpha}(N_0(t - \tau_{k+1})^\alpha) \cdots N_1(\tau_2 - \tau_1)^{\alpha-1} \\ &\quad \mathcal{E}_{\alpha,\alpha}(N_0(\tau_2 - \tau_1)^\alpha) N_1 \mathcal{E}_{\alpha,1}(N_0 \tau_1^\alpha) z_0 \\ &\quad u(\tau_{k+1}) \cdots u(\tau_1) d\tau_1 \cdots d\tau_{k+1} \\ &= \int_0^t \int_0^{\tau_{k+1}} \cdots \int_0^{\tau_2} w_{k+1}(t, \tau_{k+1}, \dots, \tau_1) \\ &\quad u(\tau_{k+1}) \cdots u(\tau_1) d\tau_1 \cdots d\tau_{k+1}. \end{aligned}$$

Thus, the expression for y_k holds for all $k \geq 0$. ■

In the case of a bilinear system corresponding to the Riemann-Liouville approach, an analogous Volterra series representation can be directly computed using Lemma 2.1. Recall also in the non-fractional case that there is a dichotomy between causal Volterra series induced by initialized state space realizations [8] and a potentially noncausal variety whose kernel functions are often derived from measurements and represented in terms of their multivariable Laplace transforms [16]. Theorem 4.1 above corresponds

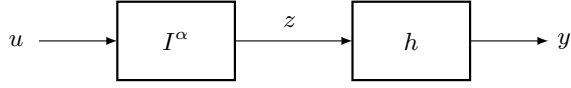


Fig. 1: Fractional Wiener system in Example 4.1

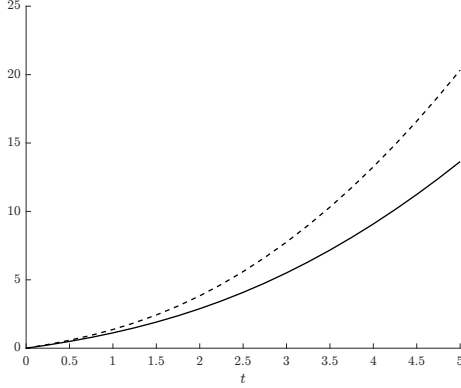


Fig. 2: Response $y(t)$ in Example 4.2 when $u(t) = t^{0.5}$ (solid line) and $\hat{y}(t) := \mathcal{E}_{0.5,1}(I^{0.5}t^{0.5})$ (dotted line) both on a logarithmic scale.

to the former in this fractional setting, while the fractional generalization of the latter has appeared in [13].

Two examples are given to illustrate the main results.

Example 4.1: Consider the scalar bilinear realization

$${}^C D^\alpha z(t) = N_1 z(t) u(t), \quad z(0) = z_0 \quad (9a)$$

$$y(t) = \lambda z(t), \quad (9b)$$

where $N_1, \lambda \in \mathbb{R}$, $u(t) = \mathbb{1}(t)$, and $0 < \alpha \leq 1$. From (7) and (8), the coefficients of the generating series are

$$(c, \eta) = \begin{cases} \lambda N_1^k z_0 & : \eta = x_1^k, k \geq 0 \\ 0 & : \text{otherwise.} \end{cases}$$

The generating series $c = \sum_{k \geq 0} x_1^k$ is clearly Gevrey of order $s = 0$ with growth constants $K = 1$ and $M = N_1$. The fractional iterated integral is

$$E_{x_1^k}^\alpha[\mathbb{1}](t) = I^{\alpha k} \mathbb{1}(t).$$

Therefore, the series representation of the output is

$$y(t) = F_c^\alpha[\mathbb{1}](t) = \lambda \sum_{k=0}^{\infty} N_1^k z_0 I^{\alpha k} \mathbb{1}(t).$$

Using Lemma 2.3, part 2 gives

$$y(t) = \lambda \mathcal{E}_{\alpha,1}(N_1 t^\alpha) z_0.$$

This system can be seen as the fractional Wiener system shown in Figure 1, where $h(z) = \mathcal{E}_{\alpha,1}(z)$, and the fractional integrator is initialized so that $z(0) = z_0$. This is the fractional version of the example given in [7] where $h(z) = e^z$. Also, note that $F_c^\alpha[\mathbb{1}](t)$ is well defined for all $t > 0$, which is consistent with Theorem 3.1 when $\gamma = s = 0$. \square

Example 4.2: Reconsider the scalar bilinear realization in (9) but now with the input $u \in L_{1/\alpha}^1[0, T]$, where $|u(t)| \leq t^{\alpha\gamma}$ for all $t \in [0, T]$ with $\gamma \in \mathbb{N}$ and $T > 0$ fixed. In this

case the series representation of the output is

$$y(t) = F_c^\alpha[u](t) = \lambda \sum_{k=0}^{\infty} N_1^k z_0 E_{x_1^k}^\alpha[u](t).$$

Lemma 3.3 yields

$$\begin{aligned} y(t) &= F_c^\alpha[u](t) \leq |\lambda| \sum_{k=0}^{\infty} |N_1|^k |z_0| \frac{(I^{\alpha t \alpha \gamma})^k}{\Gamma(\alpha k + 1)} \\ &= |\lambda| \mathcal{E}_{\alpha,1}(|N_1| I^{\alpha t \alpha \gamma}) |z_0| =: \hat{y}(t). \end{aligned} \quad (10)$$

The closed-form version of $y(t)$ can be found in [9, Example 4] and is rather complicated, but it follows from Theorem 3.1 that the series for $F_c^\alpha[u](t)$ converges absolutely and uniformly on $[0, T]$ provided $|u(t)| \leq t^{\alpha\gamma}$ for all $t \in [0, T]$ with $\alpha > s = 0$, T , and $\gamma \in \mathbb{N}$ fixed. The bounding function \hat{y} defined in (10) in terms of the Mittag-Leffler function is entire, which is also consistent with Theorem 3.1. A MatLab simulation of (9) with $N_1 = 1$, $\lambda = 1$, $z_0 = 1$, and $u(t) = t^{\alpha\gamma}$, where $\alpha = 0.5$ and $\gamma = 1$, is shown on a logarithmic scale in Figure 2 along with \hat{y} to further confirm the upper bound in (10). \square

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